


HIGH FREQUENCY GPS

Product # 90-60-397-004



 **AMZ**
YACHTING

USER MANUAL AND INSTALLATION GUIDE

V2.2

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1 OPERATION

1.1 Introduction

Thank you for purchasing the **nke High Frequency GPS**.

The **nke High Frequency GPS**, WAAS/EGNOS enabled (differential system which enhances the accuracy of GPS), is connected directly to the Topline bus and delivers data at high frequency, up to 10Hz.

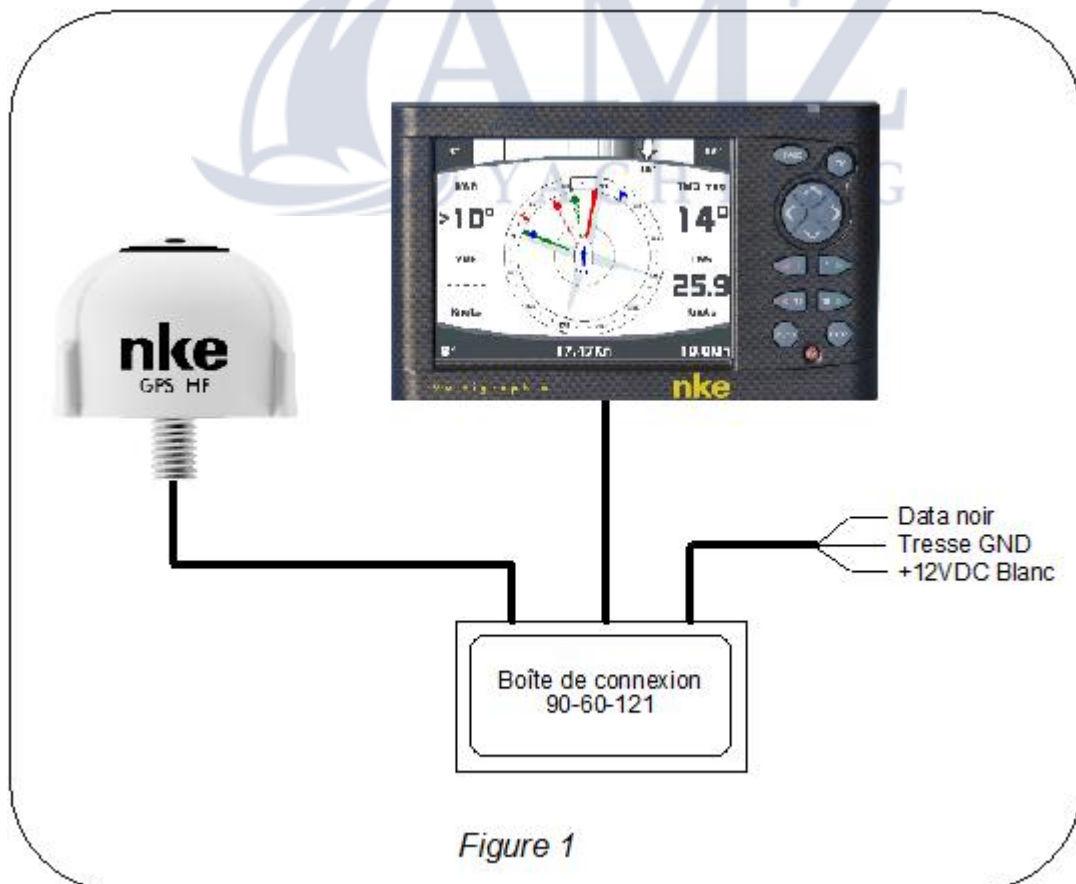
The NMEA output can be set up. Data is exported at 10Hz in NMEA format, and is compatible with the nke Processor.



IMPORTANT

Please take time to read this manual carefully before you start installation. Any connection to the **TOPLINE bus** must be performed through the specific interface box # 90-60-417 and only with the **TOPLINE bus** cable # 20-61-001.

1.2 System configuration



1.3 Technical specification

- Cold start : 29 seconds (Time To First Fix),
- Hot start : 25 seconds (Time To First Fix),
- Sensibility : -165dbm (tracking),
- Geodetic system : WGS84,
- Compatibility : WAAS/EGNOS/MSAS
- Acquisition rate : 20Hz Maximum,
- Positioning accuracy : 2,5m CEP
- Protocol : 1 Topline + 1 NMEA0183-HS (38400 bauds)
- Max consumption : 600mW
- Power supply : 9V to 33Volts (12 volts via Topline bus)
- Cable : 10m
- Protection : IP67
- Operating temperature : -10° à +50°
- NMEA version : 3.01
- Weight : 500g

1.4 List of channels displayed

When the **nke High Frequency GPS** is connected to the **Topline bus**, the following channels are created on your system.

| CHANNEL | DISPLAY | UNITS |
|--------------------|---------|-----------------------|
| Latitude | LAT | Degrees |
| Longitude | LONG | Degrees |
| Course over ground | COG | Degrees |
| Speed over ground | SOG | Knots |
| Time | TIME | Hours/minutes/seconds |
| Date | DATE | Day/month/year |
| Magnetic variation | Mag Var | Degrees |

Please note: The Latitude and Longitude channels cannot be displayed on the Gyrographic display.

In case the satellite fix is lost, the system keeps the last known data live on the **Topline bus** for 20 seconds.

When the system is switched on the error message « Fail » will be displayed as long as the **nke High Frequency GPS** has not acquired a satellite fix.

1.5 Damping the channels

The channels « SOG » and « COG » allow damping to be applied to the value displayed.

The damping level controls the rate at which the displayed value is updated. Adjustment may be required to the Speed Over Ground channel according to the sea conditions to stabilise the the value displayed.

The damping value ranges from **1** to **32**, with **8** as the default value for SOG and **2** for GOG. The lower the value, the faster the value displayed is updated.

The maintenance software Toplink, the Multigraphic (firmware V1.7) and the Multidisplay can be used to adjust this setting.

1.6 Processor compatibility

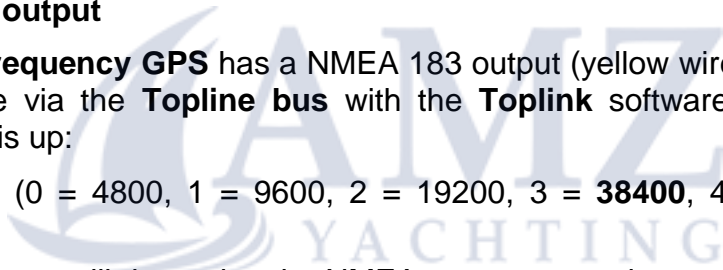
From version 2.2 of **nke High Frequency GPS** the data is permanently published on the Topline bus. In an installation including processor it will be necessary use the version 4.0 minimum to be compatible. The **High Frequency GPS** will also broadcast in NMEA0183 but this data will not have priority.

1.7 NMEA 183 output

The **nke High Frequency GPS** has a NMEA 183 output (yellow wire) that can be set up. This is done via the **Topline bus** with the **Toplink** software. Your specialist dealer can set this up:

- Baud rate (0 = 4800, 1 = 9600, 2 = 19200, 3 = **38400**, 4 = 57600 or 5 = 115200).

The Baud rate will determine the NMEA sentences and output frequency.



1.7.1 High Speed rate

The default NMEA 183 output setup complies with the NMEA-HS protocol (38400 bauds) as the table below:

| Sentence | Description | Frequency |
|----------|--|-----------|
| \$GPGGA | GPS Fix Data | 10 Hz |
| \$GPGSA | GNSS DOP and Active Satellites | 1 Hz |
| \$GPGSV | GNSS Satellites in View | 1 Hz |
| \$GPRMC | Recommended Minimum Specific GNSS Data | 20 Hz |
| \$GPVTG | Course Over Ground and Ground Speed | 1 Hz |
| \$IIXDR | Internal temperature | 1 Hz |
| \$IIXDR | Batteries voltage | 1 Hz |

1.7.2 Low speed frequency

For users who wish to set up the NMEA output at the standard 4800 Baud rate, the frequencies will be limited as shown in the table below:

| Sentence | Description | Frequency |
|----------|--|-----------|
| \$GPGGA | GPS Fix Data | 0,5 Hz |
| \$GPGSA | GNSS DOP and Active Satellites | 0,5 Hz |
| \$GPRMC | Recommended Minimum Specific GNSS Data | 5 Hz |
| \$GPVTG | Course Over Ground and Ground Speed | 0,2 Hz |
| \$IIXDR | Internal temperature | 0,2 Hz |
| \$IIXDR | Batteries voltage | 0,2 Hz |

1.8 1PPS output

The green wire is used for the GPS 1PPS output. This output ("1 pulse per second") allows synchronizing with UTC.

1.9 Audible alarm

An embedded buzzer is used to warn the users about the various working modes the **nke High Frequency GPS** antenna is using:

- Satellites search: repeated short bips (at 1Hz)
- 2D fix mode: 2 long and unique bips
- 3D fix mode: 3 long and unique bips

1.10 Magnetic variation

The magnetic variation is calculated by an algorithm from the current GPS position and a data table which is updated once every 5 years

The Magnetic Variation channel is updated every 10 minutes.

1.11 Time Offset

Using a Multigraphic V2.6 or Multidisplay V1.3 you can set a time offset from the sensor menu. See Multigraphic or Multidisplay instruction manual.

1.12 Electromagnetic compatibility

The **nke High Frequency GPS** complies with CEM regulation which are compulsory for CE certification. Relevant regulation: NF EN 60945 regarding all navigation systems and marine radio communication.

1.13 1st level trouble shooting

In this section you can find solutions to simple problems which does not require calling a specialist and without losing time. Please read carefully this manual before calling customer support.

| Trouble | Possible causes and solutions |
|---|--|
| Topline network does not display any GPS data | Please check that the GPS is correctly connected to the nke bus. When starting the system, the nke High Frequency GPS generates a short audible signal once every second. |

If the problem is not solved, please contact your nke dealer.

2 INSTALLATION

2.1 Preparing installation

Choosing the right location for the antenna is very important in order to receive an accurate GPS signal. The **nke High Frequency GPS** antenna can be mounted on a pushpit or a specific small mast. Think about the following requirements when choosing the location:

- The **nke High Frequency GPS** antenna must be installed in a location free from any objects shielding the horizon. A low location is preferable as this will ensure the best stability for the antenna.
- Choose a location far from other antennas such as radar or VHF to avoid interferences.
- Distance to a compass must exceed 30cm to avoid interference..
- Avoid the radar range.
- The antenna must be as horizontal as possible.
- On a sailing boat, avoid installing on the mast head.
- In order to reduce the noise generated by other magnetic sources such as radar, radio, engine or generators, ensure that cables run more than one meter from other cables.

2.2 Mounting

The **nke High Frequency GPS** is compatible with all standard fittings available on the market: Ø 1" (2,54cm), 14 TPI (Threads Per Inch).

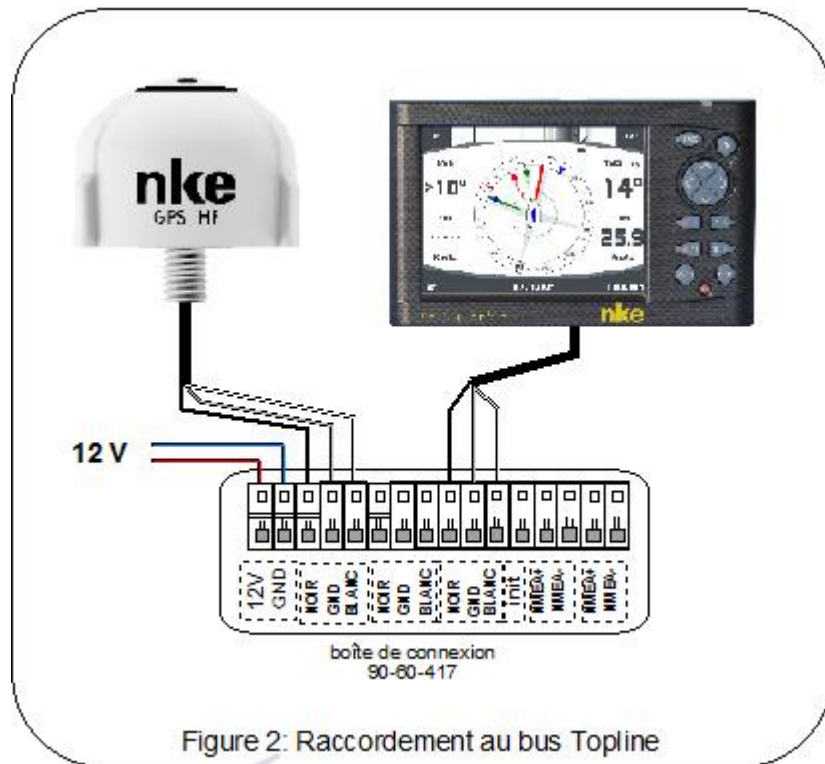
The wire can output either on the side or the centre of the fitting. The **High Frequency GPS** has no mounting direction.



WARNING

During installation, be carefull not to damage the cable. Water protection can be compromised by a dammaged cable causing serious damage to your **nke High Frequency GPS**.

2.3 Connection to the nke bus



2.4 NMEA connection



3 SOFTWARE EVOLUTION

| REV | Date | Information |
|------|------------|---|
| V1.0 | 30/05/2011 | - Original Version |
| V1.1 | 20/06/2011 | - Correction on the declination calculation |
| V1.5 | 15/07/2013 | <ul style="list-style-type: none">- Corrects a cold non-acquisition bug (backup battery discharged). Please note that the position display can be longer than 4 minutes after cold start- Allows adjustment of the heading and bottom speed filtering with a Multigraphic in version \geq V1.3- Allows you to initialize the GPS with a Multigraphic in version \geq V1.3 |
| V2.1 | 16/10/2014 | - Correction of the filtering adjustment bug on the SOG and COG with the Multigraphic |
| V2.2 | 12/02/2020 | <ul style="list-style-type: none">- New magnetic declination table 2020- Operation on the Topline Bus with processor |

Note: If you don't understand the procedures, if you have suggestions to improve this notice you can fill in a note on our web site <https://www.nke-marine-electronics.fr/>
Thank you for your contribution.

